



# IPSDK 1.5

## What's new...

## Reactiv'Ip

### **Reactiv'IP**

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### **Contact:**

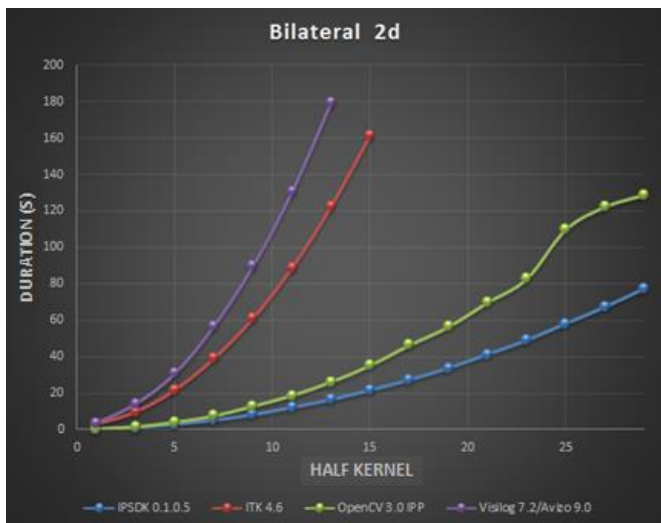
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# The product IPSDK

# IPSDK – Full set of features

- Full set of image processing features (2d/3d/sequence)
  - Morphology ( propagation, erosion, dilation, closing, ...)
  - Filtering (median, gaussian, bilateral, anisotropic diffusion, NLM, ...)
  - Thresholding (Otsu, tophat, ...)
  - Statistics, Global measures, Binary operators, color transformations, histograms, textural measures,...
  - Connected components, true distance map, correlation, Hough transform, Watershed,...
  - Blob analysis: many measures (form, intensity, orientation, ...)



# IPSDK Library - Scripting

```

# import of IPSDK library
import PyIPSDK
import PyIPSDK.IPSDKIPLAdvancedMorphology as advmorpho
import PyIPSDK.IPSDKIPLBinarization as bin
import PyIPSDK.IPSDKIPLShapeAnalysis as shapeanalysis

# opening of input images
inGreyImg = PyIPSDK.loadTiffImageFile("G:/Sample/blobs_483x348_UInt8.tif")

# automatic binarization
inBinImg, thrValue = bin.otsuThresholdImg(inGreyImg)

# connected component analysis
inLabelImg2d = advmorpho.connectedComponent2dImg(inBinImg)

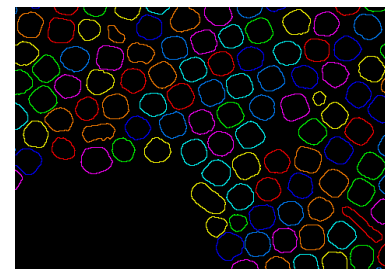
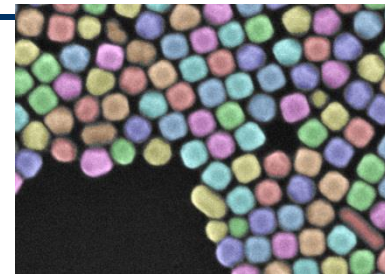
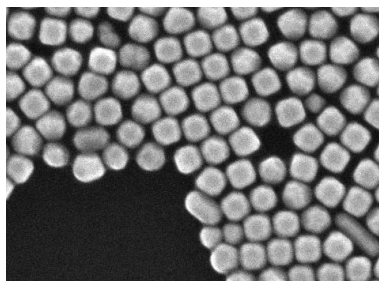
# extraction of associated shapes
inShape2dColl = shapeanalysis.labelContourExtraction2d(inLabelImg2d)

# definition of proceeded measure
inMsrInfoSet = PyIPSDK.createMeasureInfoSet2d()
PyIPSDK.createMeasureInfo(inMsrInfoSet, "Circularity2dMsr")

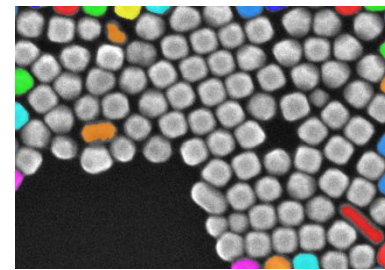
# shape analysis
outMeasureSet = shapeanalysis.shapeAnalysis2d(inGreyImg, inShape2dColl, inMsrInfoSet)

# shape filtering computation
outImg = shapeanalysis.shapeFiltering2dImg(inLabelImg2d, inGreyImg, "Circularity2dMsr < 0.9")

```



Label Index	Circularity2d	Area2d	Perimeter2d
1	0,73	19,5	21,3
2	0,65	20,0	24,5
3	0,77	260,0	74,6
4	0,82	300,5	74,8
5	0,85	447,0	88,6
6	0,74	220,0	70,8
...	...	...	...
111	0,86	435,0	85,7
112	0,78	339,5	83,2
113	0,59	6,5	15,4



## Evolutions



- New supported OS,
- Better integration in Python IDE, new tools,
- New image processing features,
- Perspectives...



# New compatible OS

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## **IPSDK 1.5 is now usable on:**

- Windows 7, 8, 10
- Linux Ubuntu 14.04 and more recent
- Linux Suse
- Linux Debian 8

Compilers: gcc and Visual Studio 2015 express

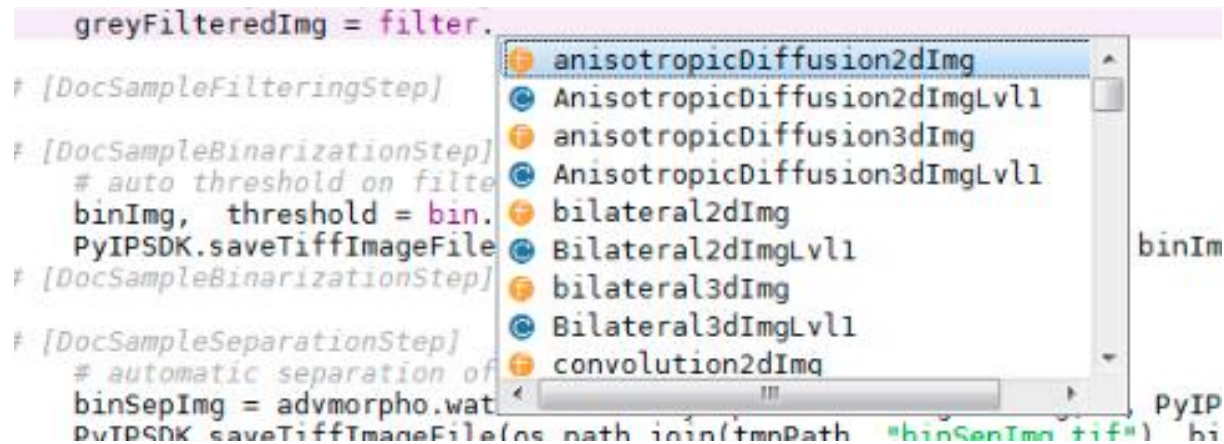
Python 3.5

# Simplifying use with Python

- Autocompletion

```

greyFilteredImg = filter.
# [DocSampleFilteringStep]
# [DocSampleBinarizationStep]
# auto threshold on filtered image
binImg, threshold = binarize(greyFilteredImg, threshold = bin.
PyIPSDK.saveTiffImageFile(binImg, threshold, binImg)
# [DocSampleBinarizationStep]
# [DocSampleSeparationStep]
# automatic separation of the image into foreground and background
binSepImg = advmorpho.watershed(binImg)
PyIPSDK.saveTiffImageFile(os.path.join(tmpPath, "binSepImg.tif"), binSepImg)
  
```



- Simplified access to structure fields

```

# statistics measurement
statsMsrResult = gblmsr.statsMsr3d(inImg)

# retrieve measurement results
mean = statsMsrResult.mean
  
```

# Simplifying use with Python

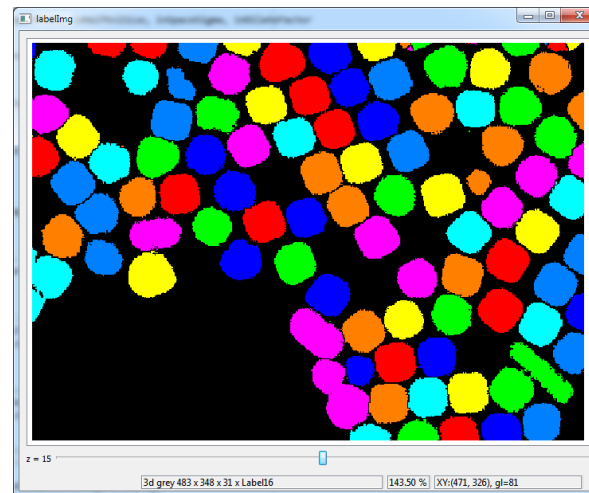
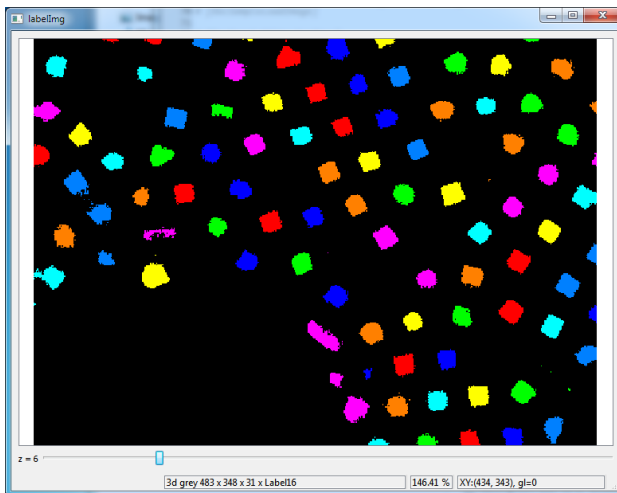


Ability to **display** images in scripts to help implementation

```
import PyIPSDK.IPSDKUI as gui
```

```
labelImg = advmorpho.connectedComponent3dImg(binSepImg)
```

```
labelImgView = gui.displayImg(labelImg, "labelImg")
```



2D display, but possibility to navigate inside 3D or sequence image with the slider

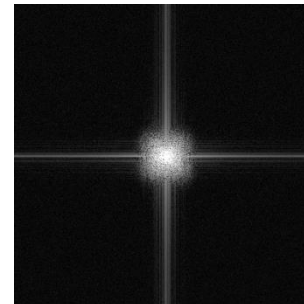
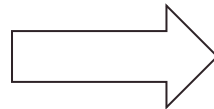
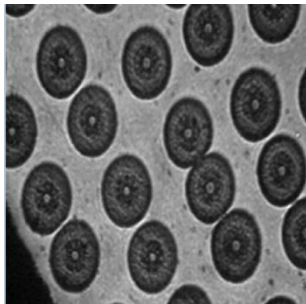


# New Image Processing Features

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## 2D and 3D FFT:

- Forward FFT,
- Backward FFT,
- Polar to cartesian coordinates transformation,
- Cartesian to polar coordinates transformation



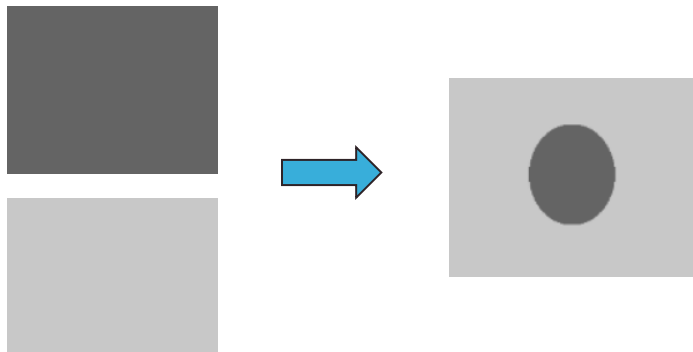
# New Image Processing Features

## Generation of an image using a formula string (formula 2d/3d Img)

```
outBinImg = arithm.formula2dImg("if(sqrt((x-cx)*(x-cx)+(y-cy)*(y-cy))<=10, True, False)",
    InOptImg1=inImg)
```



```
outImg = arithm.formula2dImg("if(sqrt((x-cx)*(x-cx)+(y-cy)*(y-cy))<=50, I1, I2)",
    InOptImg1=inImg1, InOptImg2=inImg2)
```



# New Image Processing Features

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## Generation of an image using a formula string (formula 2d/3d Img)

**formula2dimg**("mean(rect(I1, 3, 2))", InOptImg1=inImg)

 Mean filter with rectangular neighborhood

**formula2dimg**("mean(circle(I1, 4))", InOptImg1=inImg)

 Mean filter with circular neighborhood

# New Image Processing Features

## Resampling along Z axis

- Resampling from regular slice spaces

➡ Useful if a distance map must be calculated

- Resampling from non regular slice spaces

➡ Useful in FIB or confocal microscopy

```
// specify distances between z-planes in input 3d image
boost::shared_ptr<attr::ZSteps> pZSteps = attr::ZSteps::createNode();
pZSteps->push_back<attr::ZSteps::StepsColl>(0.990f); // distance between image #0 a
pZSteps->push_back<attr::ZSteps::StepsColl>(1.015f); // distance between image #1 a
pZSteps->push_back<attr::ZSteps::StepsColl>(0.988f); // distance between image #2 a
pZSteps->push_back<attr::ZSteps::StepsColl>(0.994f); // distance between image #3 a
pZSteps->push_back<attr::ZSteps::StepsColl>(1.007f); // distance between image #4 a
pZSteps->push_back<attr::ZSteps::StepsColl>(0.995f); // distance between image #5 a
pZSteps->push_back<attr::ZSteps::StepsColl>(0.997f); // distance between image #6 a
```

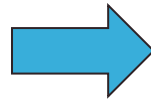
```
resampleCustomZstack3dImg(pInImg, pZSteps, 8, attr::eInterpolationPolicy::eIP_Linear);
```

# New Image Processing Features



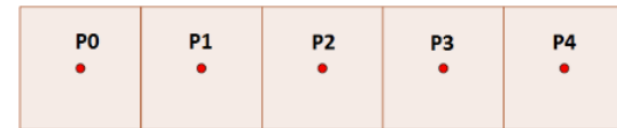
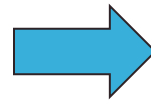
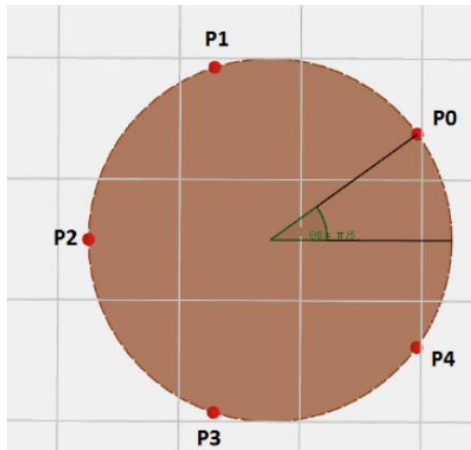
## Image cylinder unrolling:

Algorithm unfolding a cylinder contained in a 3D input image into a 2D output image



# New Image Processing Features

## Image cylinder unrolling:

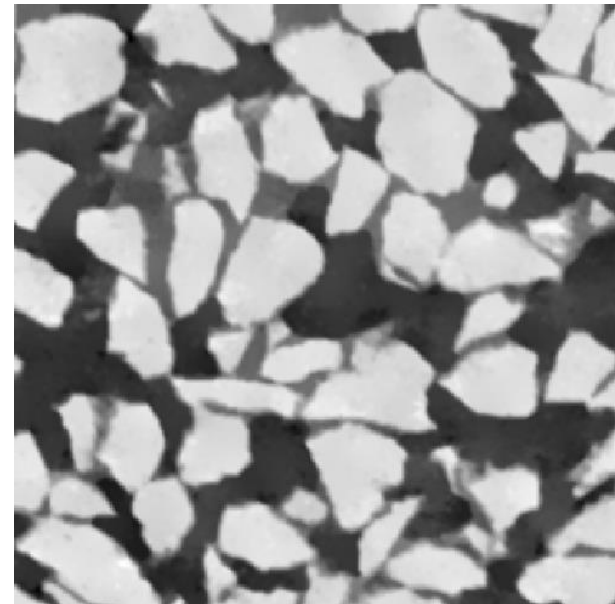
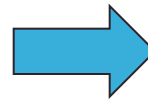
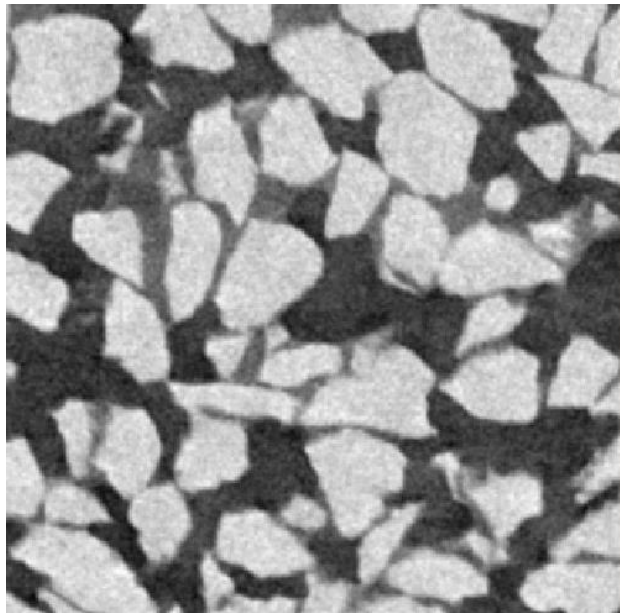


- Several resampling options (linear, cubic, nearest),
- Thickness size editable,
- Several options for the thickness integration (min, max, mean)

# New Image Processing Features

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- **Despeckle 2D and 3D**
  - Replace aberrant pixels by the median value of their neighborhoods
- **Sobel gradient 2D and 3D**
- **Patch-based bilateral smoothing 2D and 3D**
  - Optimized version of the Non Local Mean algorithm



# New statistical measures

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- Local entropy
- Local energy
- Local histogram module
- Law's texture energy measures
- Masked histogram

Histogram of the portion of an image (portion is defined by a mask image)



# Detection and registration

## Detection:

- Canny edges 2D detector
- Canny edges 3D detector
- Harris corners

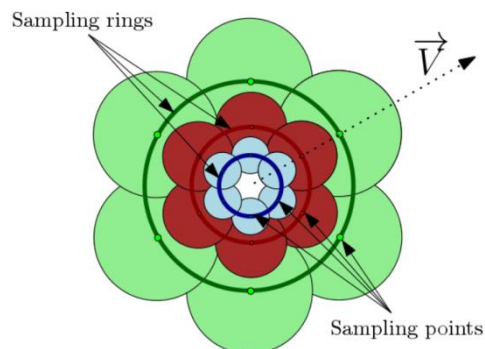
Edge extraction (image 2D)

Surface extraction (image 3D)

Corner extraction (2D et 3D)



- **Extract grey signed features** Extraction of grey signed features from image



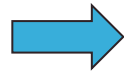
Signature independent of rotation and zoom factor

# Detection and registration



## Registration:

- **greySignedFeaturesImg** Computation of motion transform linking two images based on a grey signed features algorithm



Translation, rotation, Homothety



# Detection and registration



In blue: All corner points detected

In Green: All corner points linked



# Classification by pixel

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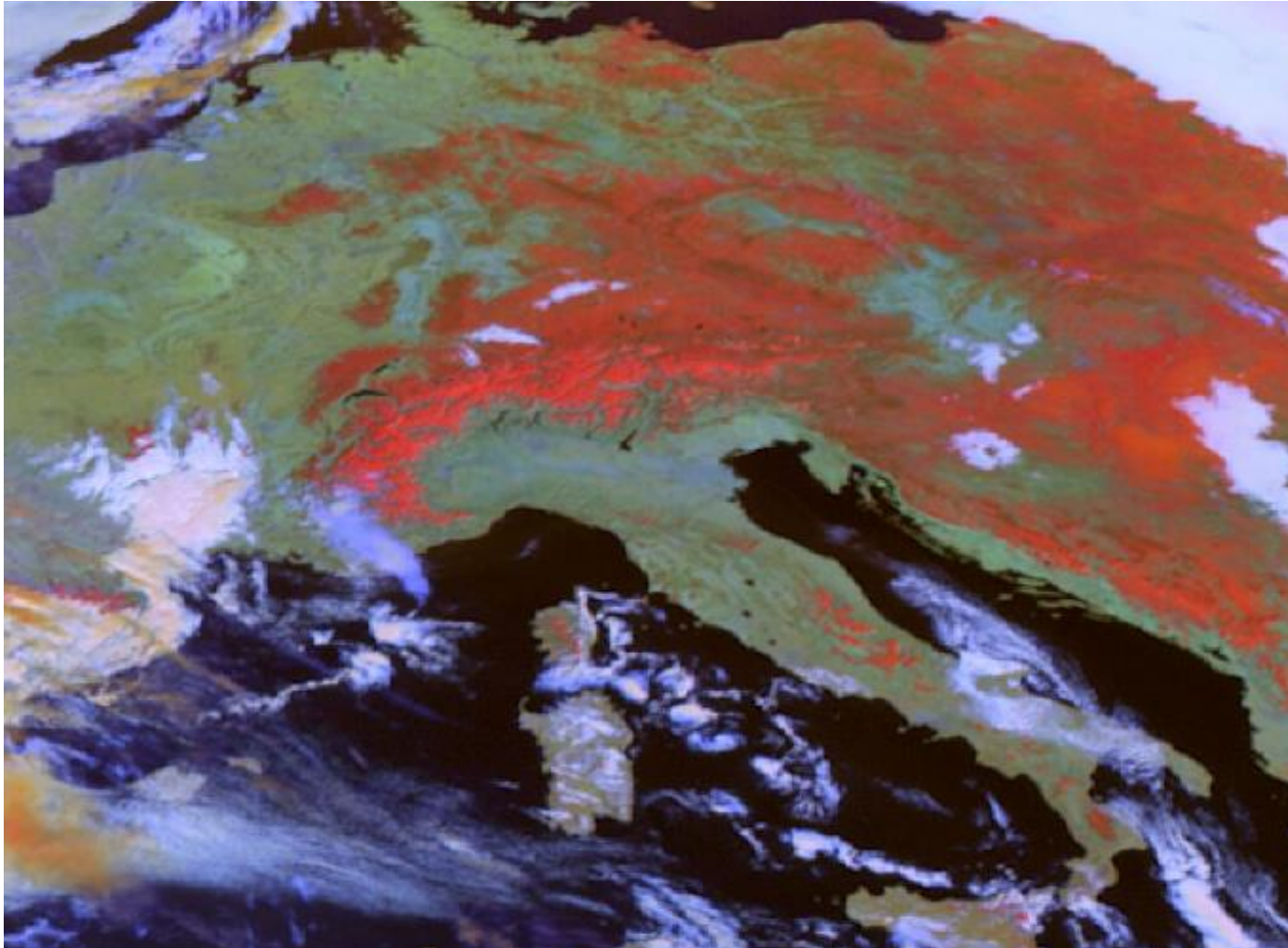
- **K-Means**      2D and 3D pixel K-mean classification
- Classification    by imposing the number of classes
- Classification    by training (center of classes description)
  - ➔ **kMeansAssignImg, kMeansComputeCenters, kMeansImg,...**
- Use:
  - With color images (or multi-spectral)
  - With vector of texture (one image by attribute)



# Classification by pixel

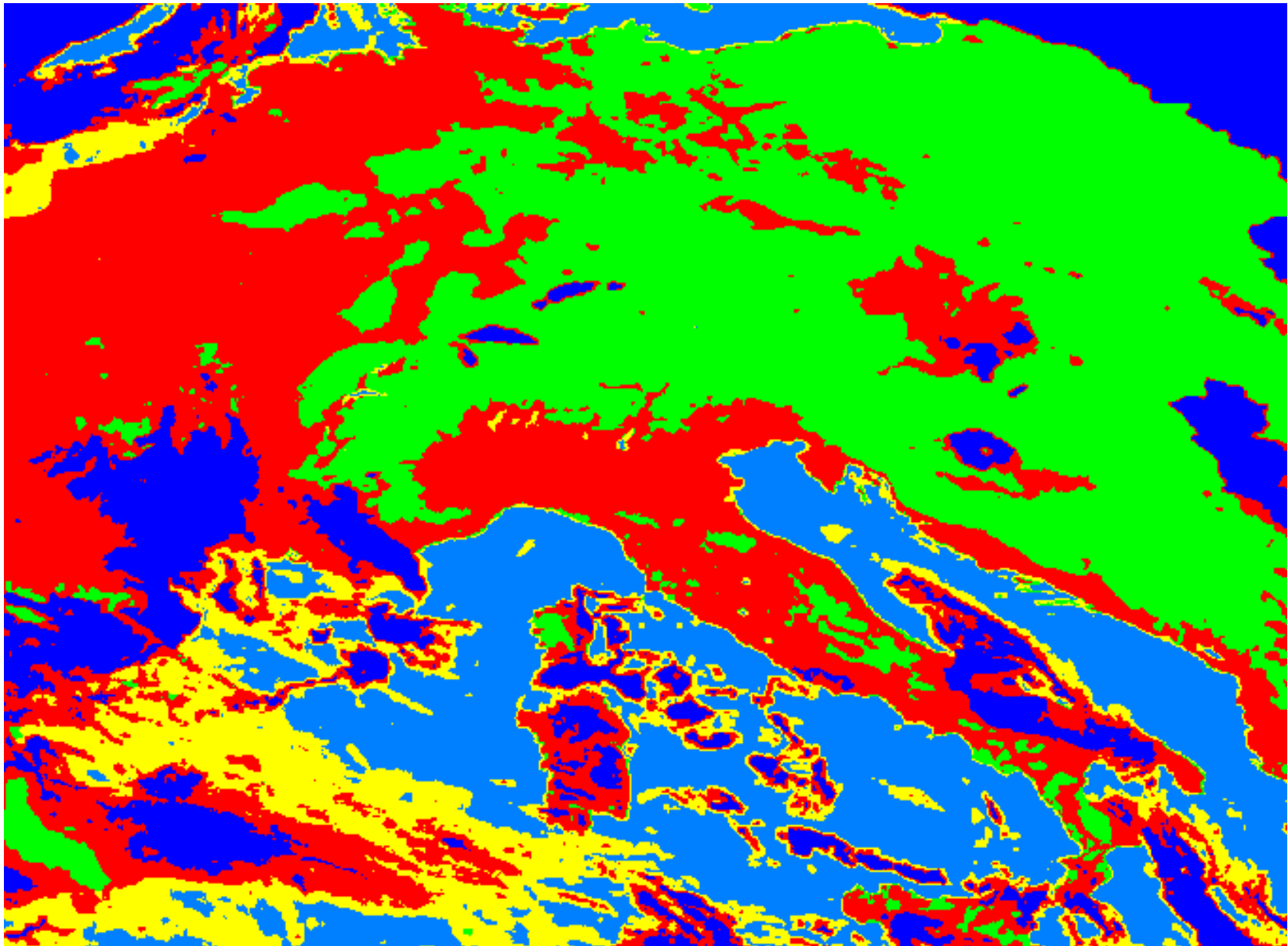
---

Sample: Automatic classification using K-Mean with 5 classes



# Classification by pixel

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# Perspectives

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- GPU computation,
- Increase of scalability,
  
- And many other innovative image processing features!

IPSDK evaluation version is available  
Feel free to ask it !

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